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SHORT-RANGE RADAR IMPLEMENTED WITH ULTRASOUND SENSOR AND PSoC5LP

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ABSTRACT

This document presents the design and construction of a short-range radar (up to 4 meters) making use of an ultrasound sensor with which it performs a constant 2D scan of the environment, displayed on a monochromatic graphic LCD of 128x64 pixels, the radar scan is performed in a 180° rotation range making use of a servo motor for this task, a trace of the objects detected by the radar must be plotted on the screen, with typical application in mobile robotics.

KEYWORDS: Graphic LCD, Mobile Robotic, PSoC5LP, Servomotor, Ultrasound Sensor

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